Data Structures – LECTURE 13

Minumum spanning trees

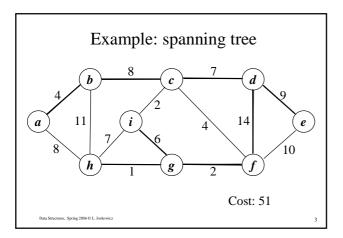
- Motivation
- Properties of minimum spanning trees
- Kruskal's algorithm
- Prim's algorithm

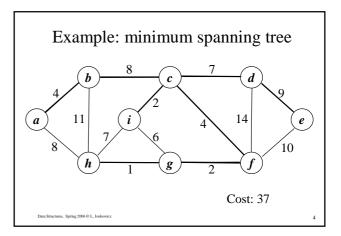
Chapter 23 in the textbook (pp 561—579).

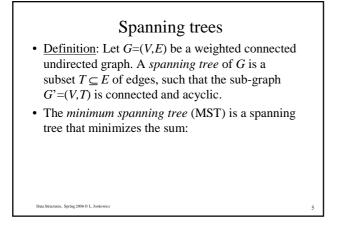
Motivation

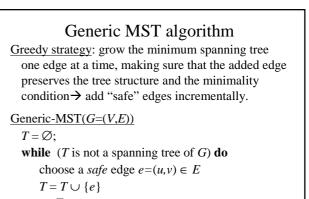
- Given a set of nodes and possible connections with weights between them, find the subset of connections that connects all the nodes *and* whose sum of weights is the smallest.
- Examples:
 - telephone switching network
 - electronic board wiring
- The nodes and subset of connections form a tree!
- This tree is called the Minimum Spanning Tree (MST – עץ פורש מינימום)

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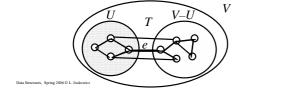


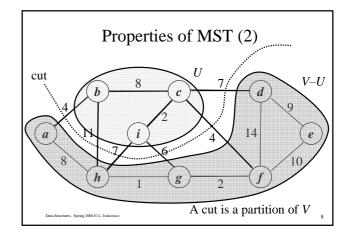


return T

Properties of MST (1)

- Question: how to find *safe edges* efficiently?
- Theorem 1: Let and e = (u, v) be a minimum weight edge with one endpoint in U and the other in V–U. Then there exists a minimum spanning tree T such that e is in T.



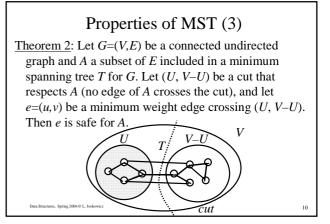


Properties of MST (2)

Proof: Let *T* be an MST. If *e* is not in *T*, add *e* to *T*. Because T is a tree, the addition of e creates a cycle which contains e and at least one more edge e' = (u', v'), where $u' \in U$ and $v' \in V - U$.

Clearly, $w(e) \le w(e')$ since *e* is of minimum weight among the edges connecting U and V-U. We can thus delete *e*' from *T*.

The resulting $T' = T - \{e'\} \cup \{e\}$ is a tree whose weight is less or equal than that of $T: w(T') \le w(T)$.



Properties of MST (4)

Proof: Define an edge e to be a light edge crossing a cut if its weight is the minimum crossing the cut.

Let T be an MST that includes A, and assume T does not contain the light edge e = (u, v) (if it does, e is safe). Construct another MST T' that includes $A \cup \{e\}$. The edge forms a cycle with edges on the path p from u to v in T. Since *u* and *v* are on opposite sides of the cut, there is at least one edge e' = (x, y) in *T* on the path *p* that also crosses the cut. The edge e' is not in A because the cut respects A. Since e' is on the unique path from u to v in T, removing it breaks T into two components.

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Properties of MST (5)

Adding e = (u, v) reconnects the two components to form a new spanning tree:

 $T' = T - \{e'\} \cup \{e\}$

We now show that T' is a MST. Since e = (u, v) is a light edge crossing (U, V-U) and e' = (x, y) also crosses this cut, $w(u,v) \le w(x,y)$. Thus: w

$$w(T') = w(T) - w(u,v) + w(x,y)$$

$$\leq w(T)$$

Since *T* is an MST and $w(T') \le w(T)$, then w(T') = w(T)and T' is also an MST.

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Properties of MST (6)

<u>Corollary</u>: Let G=(V,E) be a connected undirected graph and A a subset of E included in a minimum spanning tree T for G, and let $C = (V_C, E_C)$ be a tree in the forest $G_A = (V,A)$. If e is a light edge connecting C to some other component in G_A , then e is safe for A.

<u>Proof</u>: The cut $(V_C, V-V_C)$ respects A, and e is a light edge for this cut. Therefore, e is safe.

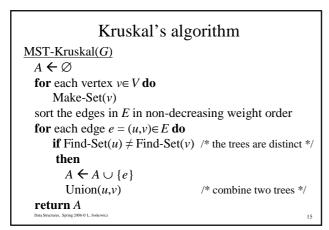
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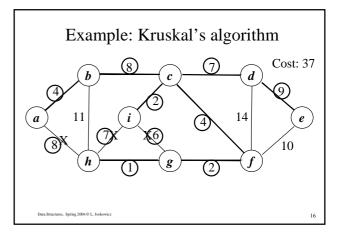
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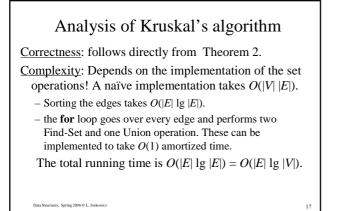
Two algorithms to find an MST

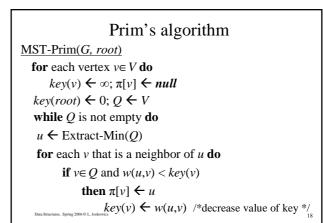
There are two ways of adding a safe edge:

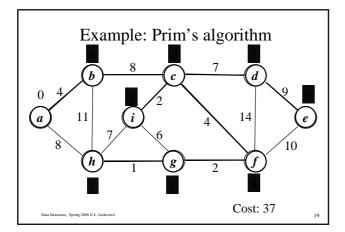
- 1. <u>Kruskal's algorithm</u>: the set *A* is a forest and the safe edge added is always the least-weight edge in the graph connecting two distinct components (Theorem 2).
- 2. <u>Prim's algorithm</u>: the set *A* is a tree and the safe edge added is always the least-weight edge connecting *A* to a vertex not in *A* (Theorem 1).











Analysis of Prim's algorithm <u>Correctness</u>: follows directly from the Theorem 1.

<u>Complexity</u>: Depends on the implementation of the minimum priority queue. With a binary mean-heap, we have:

- Building the initial heap takes O(|V|).
- Extract-Min takes $O(\lg |V\!/)$ per vertex \rightarrow total $O(|V|\lg |V\!/)$
- The **for** loop is executed O(|E|).

– Membership test is O(1). Decreasing a key is $O(\lg |V|)$.

Overall, the running time is $O(|V| \lg |V| + |E| \lg |V|) = O(|E| \lg |V|)$.

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Summary: MST

- MST is a tree of all nodes with minimum total cost
- Two greedy algorithms for finding MST:
 - Kruskal's algorithm: edge-based. Runs in O(|V| |E|).
 - Prim's algorithm: vertex-based. Runs in $O(|E/\lg/V/)$.
- Complexity of Kruskal's algorithm can be improved with Union-Find ADT to $O(|E| \lg |V|)$,
- Complexity of Prim's algorithm can be improved with Fibonacci heaps to $O(|V| \lg |V| + |E|)$.
- Randomized algorithm has O(|V| + |E|) expected time.

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