

Supplementary Material for Paper: Discriminative Learning of Infection Models

1 Independent Cascade Model

The independent cascade (IC) model dynamics is equivalent to the following. First, sample each edge $e \in E$ to be *active* independently with probability θ_e . Then, the infected nodes are those reachable in the active network from some node in the seed s .

The integral in the kernel entries can be simplified (for simplicity we assume $\Theta = [0, 1]^{|E|}$):

$$\begin{aligned} K(x, x') &= \int_{\Theta} f(s; \theta) f(s'; \theta) d\theta = \int_{\Theta} \mathbb{E}_{\theta}[y|s] \mathbb{E}_{\theta}[y|s'] d\theta \\ &= \int_{\Theta} \left(\sum_{A \subseteq E} P_{\theta}(A) r(A, s) \right) \left(\sum_{A' \subseteq E} P_{\theta}(A') r(A', s') \right) d\theta \\ &= \sum_{A, A' \subseteq E} r(A, s) r(A', s') \int_{\Theta} P_{\theta}(A) P_{\theta}(A') d\theta \end{aligned}$$

With a uniform prior over θ , marginalizing over θ gives us a joint distribution Q over A, A' :

$$Q(A, A') = \int_{\Theta} P(A, A', \theta) d\theta = \int_{\Theta} P(A|\theta) P(A'|\theta) P(\theta) d\theta = \frac{1}{|\Theta|} \int_{\Theta} P_{\theta}(A) P_{\theta}(A') d\theta$$

Now we can write:

$$K(x, x') \propto \sum_{A, A' \subseteq E} r(A, s) r(A', s') q(A, A') = \mathbb{E}_q[r(A, s) r(A', s')]$$

When each θ_e is integrated over $[a, b]$, using edge independence we get:

$$\begin{aligned} Q(A, A') &= \frac{1}{|\Theta|} \int_{\Theta} P_{\theta}(A) P_{\theta}(A') d\theta \\ &= \frac{1}{|\Theta|} \int_{\Theta} \prod_{e \in A} \theta_e \prod_{\bar{e} \notin A} (1 - \theta_{\bar{e}}) \prod_{e' \in A'} \theta_{e'} \prod_{\bar{e}' \notin A'} (1 - \theta_{\bar{e}'}) d\theta \\ &= \frac{1}{(b-a)^{|E|}} \int_{\Theta} \prod_{e \in A \cap A'} \theta_e^2 \prod_{\bar{e} \in A \setminus A'} \theta_{\bar{e}} (1 - \theta_{\bar{e}}) \prod_{\hat{e} \in A' \setminus A} \theta_{\hat{e}} (1 - \theta_{\hat{e}}) \prod_{\bar{e} \in \overline{A \cup A'}} (1 - \theta_{\bar{e}})^2 d\theta \\ &= \left(\frac{1}{b-a} \int_a^b u^2 du \right)^{|A \cap A'|} \left(\frac{1}{b-a} \int_a^b u(1-u) du \right)^{|A \setminus A'| + |A' \setminus A|} \left(\frac{1}{b-a} \int_a^b (1-u)^2 du \right)^{|\overline{A \cup A'}|} \\ &= q_{\cap}^{|A \cap A'|} q_{\oplus}^{|A \setminus A'|} q_{\oplus}^{|A' \setminus A|} q_{\cup}^{|\overline{A \cup A'}|} \end{aligned}$$

where $q_{\cap} = \frac{b^3 - a^3}{3(b-a)}$, $q_{\oplus} = \frac{b^2 - a^2}{2(b-a)} - \frac{b^3 - a^3}{3(b-a)}$, and $q_{\cup} = \frac{b^3 - a^3}{3(b-a)} - \frac{b^2 - a^2}{b-a} + 1$. This suggests that under q , each edge is independently drawn to be in both A and A' with probability q_{\cap} , in either A or A' (but not in

both) with probability q_{\oplus} , and in neither with probability q_{\ominus} . Hence, the computational difficulty of computing the kernel entries reduces from estimating influence over IC model parametrization given by all (or a large sample of) θ -s to simply estimating ‘co-influence’ under a single ‘co-IC’ parametrization given by q .

Grouped Cascade Model In this generalization of the IC model, each node is a-priori assigned to one of K groups. As in the IC model, when a node i is infected, he has a single attempt to infect each of his non-infected neighbors j . In the grouped cascade model (GC), neighbors in the same group are “tied” - i independently infects *all* nodes in a group $k \in [K]$ with probability θ_{ik} , and *none* with probability $1 - \theta_{ik}$. When for every node i each neighbor j is in a different group (for instance when $K = n$), this model is equivalent to the IC model. Computing the kernel matrix for the GC model is similar to the IC model - instead of having a product over edges (i, j) , our product will be over node-group pairs (i, k) . To sample active edge sets A, A' under this model, for each i and $k \in [K]$ we sample all edges $\{(i, j) \in E : g(j) = k\}$ to be in both A and A' , only one of them, or neither of them, according to Q_{ik}^{IC} .

2 Linear Threshold Model

In the linear threshold (LT) model, each neighbor j of node i has weight θ_{ji} , with $\sum_j \theta_{ji} \leq 1$. In each instance, each node i first samples a threshold $\tau_i \sim U[0, 1]$. Then, a node i is infected if the sum of weights of his infected neighbors is higher than his threshold.

An equivalent process is as follows: First, for each node i , at most one incoming edge (j, i) becomes active with probability θ_{ji} (and no edge is active with probability $1 - \sum_j \theta_{ji}$). Then, the set of infected nodes are those for which there exists an active path from some seed node.

The kernel entries can be simplified. Denote by S^d the d -dimensional simplex, $S_i = S^{|N(i)|}$, and $\Theta = S_1 \times \dots \times S_n$. As in the independent cascade kernel, the challenge is computing the integral over the product of probabilities. First, consider a joint distribution over (A, A', θ) with a uniform prior $P(\theta) = \frac{1}{|\Theta|} = 1 / \prod_i |S_i|$, and A, A' are independent given θ . By marginalizing out θ we can write:

$$\begin{aligned} P(A, A') &= \int_{\Theta} P(A, A', \Theta) d\theta = \int_{\Theta} P(A|\theta)P(A'|\theta)P(\theta) d\theta \\ &= \prod_i \frac{1}{|S_i|} \int_{S_i} P_{\theta}(A_{\cdot i})P_{\theta}(A'_{\cdot i}) d\theta_{\cdot i} = \prod_i P(A_{\cdot i}, A'_{\cdot i}) d\theta \end{aligned}$$

Recall that at most one entry in $A_{\cdot i}$ is on - denote it by $A(i) \in [N(i)] \cup \phi$ (and $A'(i)$ for A'). When $A(i) \neq A'(i)$, we have:

$$\frac{1}{|S_i|} \int_{S_i} P_{\theta}(A_{\cdot i})P_{\theta}(A'_{\cdot i}) d\theta_{\cdot i} = d! \int_{S^d} u_1 \cdot u_2 \dots du_d = \frac{d!}{(d+2)!} = \frac{1}{(d+1)(d+2)}$$

and when $A(i) = A'(i)$, we have:

$$\frac{1}{|S_i|} \int_{S_i} P_{\theta}(A_{\cdot i})P_{\theta}(A'_{\cdot i}) d\theta_{\cdot i} = d! \int_{S^d} (u_1)^2 du_1 \dots du_d = 2 \frac{d!}{(d+2)!} = \frac{2}{(d+1)(d+2)}$$

since¹:

$$\int_{S^d} u_1^{\ell_1} \dots u_d^{\ell_d} \cdot (1 - \sum_{k=1}^d u_k)^{\ell_0} = \frac{\prod_{k=0}^d \ell_k!}{\left(\sum_{k=0}^d \ell_k + d\right)!}$$

¹<http://math.stackexchange.com/questions/207073/definite-integral-over-a-simplex>

Once again we attained a distribution from which we can sample co-influences, this time under the linear threshold model: for each node i , we draw a joint edge (or no edges) with probability $\frac{2}{(d+1)(d+2)}$, and different edges (or no edges) with probability $\frac{1}{(d+1)(d+2)}$.

3 Branching Pocesesses

In a branching process, a tree is generated by recursively sampling the number of children a node in the tree has from some fixed distribution. We use multi-type branching processes, where a node can either be *active* (and can have children) or *passive* (and cannot have children). The expected number of offspring μ_ℓ at depth ℓ is given by recursion:

$$\mu_0 = \begin{pmatrix} 1 & 0 \end{pmatrix}, \quad M = \begin{pmatrix} \mu_a & \mu_p \\ 0 & 0 \end{pmatrix}, \quad \mu_\ell = \mu_{\ell-1} \cdot M = \mu_0 \cdot M^\ell \quad (1)$$

Where μ_a, μ_p are the expected number of active and passive children of a given node. A node i receives $1/2^\ell$ credit for each offspring at distance ℓ (with maximal depth δ). The expected credit of i is therefore:

$$\text{credit}(i) = c(x^i) = \sum_{\ell=1}^{\delta} \frac{1}{2^\ell} (\mu_a^\ell + \mu_a^{\ell-1} \mu_p) \quad (2)$$

When the number of children are drawn from the geometric distribution with parameters θ , we get $\mu = \frac{1}{\theta} - 1$. In our model, θ is set to be:

$$\theta(x; w,) = \frac{1}{1 + e^{-\langle w, x \rangle + b}} \Rightarrow \mu = e^{-\langle w, x \rangle + b} \quad (3)$$

where x are a node's features and w, b are weights. We present a closed form solution for the kernel entries. Define $\mathbf{w} = (w_a, b_a, w_p, b_p)$, then:

$$\begin{aligned} K(x, x') &= \int c(x; w) c(x'; w) d\mathbf{w} = \int \left(\sum_{\ell=1}^{\delta} \frac{1}{2^\ell} (\mu_a^\ell + \mu_a^{\ell-1} \mu_p) \right) \left(\sum_{\ell'=1}^{\delta} \frac{1}{2^{\ell'}} (\mu_a^{\ell'} + \mu_a^{\ell'-1} \mu_p) \right) d\mathbf{w} \\ &= \sum_{\ell, \ell'=1}^{\delta} \frac{1}{2^{\ell+\ell'}} \int (\mu_a^\ell + \mu_a^{\ell-1} \mu_p) (\mu_a^{\ell'} + \mu_a^{\ell'-1} \mu_p) d\mathbf{w} \\ &= \sum_{\ell, \ell'=1}^{\delta} \frac{1}{2^{\ell+\ell'}} \left(\underbrace{\int \mu_a^\ell \mu_a^{\ell'} d\mathbf{w}}_{(I)} + \underbrace{\int \mu_a^\ell \mu_a^{\ell'-1} \mu_p d\mathbf{w}}_{(II)} + \underbrace{\int \mu_a^{\ell-1} \mu_p \mu_a^{\ell'-1} \mu_p d\mathbf{w}}_{(II)'} + \underbrace{\int \mu_a^{\ell-1} \mu_p \mu_a^{\ell'-1} \mu_p d\mathbf{w}}_{(III)} \right) \end{aligned}$$

with:

$$\begin{aligned} (I) &= \int \left(e^{-\langle w_a, x \rangle + b_a} \right)^\ell \left(e^{-\langle w_a, x' \rangle + b_a} \right)^{\ell'} d\mathbf{w} \\ &= \int dw_p \int db_p \int e^{-\langle w_a, \ell x + \ell' x' \rangle + b_a(\ell + \ell')} dw_a db_a \\ &= V_{w_p} V_{b_p} \int e^{b_a(\ell + \ell')} db_a \prod_k \int e^{-(w_a)_k \overbrace{(\ell(x_a)_k + \ell'(x'_a)_k)}^{\alpha_k^1}} d(w_a)_k \\ &= V_{w_p} V_{b_p} \frac{1}{\ell + \ell'} \left[e^{b_a(\ell + \ell')} \right]_{b_a^{\min}}^{b_a^{\max}} V_{w_a}^{|\{k: \alpha_k^1 = 0\}|_S} \prod_{k: \alpha_k^1 \neq 0} \frac{1}{\alpha_k^1} \left[e^{-(w_a)_k \alpha_k^1} \right]_{(w_a)_k^{\max}}^{(w_a)_k^{\min}} \quad (*) \end{aligned}$$

$$\begin{aligned}
(\text{II}) &= \int \left(e^{-\langle w_a, x \rangle + b_a} \right)^\ell \left(e^{-\langle w_a, x' \rangle + b_a} \right)^{\ell'-1} e^{-\langle w_p, x' \rangle + b_p} d\mathbf{w} \\
&= \int e^{b_p} db_p \int e^{b_a(\ell+\ell'-1)} db_a \prod_k \int e^{-(w_p)_k x'_k} d(w_p)_k \int e^{-(w_a)_k \overbrace{(\ell x_k + (\ell'-1)x'_k)}^{\alpha_k^2}} d(w_a)_k \\
&= \left[e^{b_p} \right]_{b_p^{\min}}^{b_p^{\max}} \frac{1}{\ell + \ell' - 1} \left[e^{b_a(\ell+\ell'-1)} \right]_{b_a^{\min}}^{b_a^{\max}} \dots \\
&\quad V_{w_p}^{|\{k: x'_k=0\}|} \prod_{k: x'_k \neq 0} \frac{1}{x'_k} \left[e^{-(w_p)_k x'_k} \right]_{(w_p)_k^{\max}}^{(w_p)_k^{\min}} V_{w_a}^{|\{k: \alpha_k^2=0\}|} \prod_{k: \alpha_k^2 \neq 0} \frac{1}{\alpha_k^2} \left[e^{-(w_a)_k \alpha_k^2} \right]_{(w_a)_k^{\max}}^{(w_a)_k^{\min}}
\end{aligned} \tag{*}$$

$$\begin{aligned}
(\text{III}) &= \int \left(e^{-\langle w_a, x \rangle + b_a} \right)^{\ell-1} e^{-\langle w_p, x \rangle + b_p} \left(e^{-\langle w_a, x' \rangle + b_a} \right)^{\ell'-1} e^{-\langle w_p, x' \rangle + b_p} \\
&= \int e^{2b_p} db_p \int e^{(\ell+\ell'-2)b_a} db_a \prod_k \int e^{-(w_p)_k (x_k + x'_k)} d(w_p)_k \int e^{-(w_a)_k \overbrace{((\ell-1)x_k + (\ell'-1)x'_k)}^{\alpha_k^3}} d(w_a)_k \\
&= \frac{1}{2} \left[e^{2b_p} \right]_{b_p^{\min}}^{b_p^{\max}} \frac{1}{\ell + \ell' - 2} \left[e^{b_a(\ell+\ell'-2)} \right]_{b_a^{\min}}^{b_a^{\max}} \dots \\
&\quad V_{w_p}^{|\{k: x_k + x'_k=0\}|} \prod_{k: x_k + x'_k \neq 0} \frac{1}{(x_k + x'_k)} \left[e^{-(w_p)_k (x_k + x'_k)} \right]_{(w_p)_k^{\max}}^{(w_p)_k^{\min}} \dots \\
&\quad V_{w_a}^{|\{k: \alpha_k^3=0\}|} \prod_{k: \alpha_k^3 \neq 0} \frac{1}{\alpha_k^3} \left[e^{-(w_a)_k \alpha_k^3} \right]_{(w_a)_k^{\max}}^{(w_a)_k^{\min}}
\end{aligned} \tag{*}$$

(*) when the denominator is 0, $[e^{-x}]_{x^{\min}}^{x^{\max}}$ is replaced with $x^{\max} - x^{\min}$