

# Viewing in 3D

## Viewing in 3D

- How to specify which part of the 3D world is to be viewed?
  - ♦ 3D viewing volume
- How to transform 3D world coordinates to 2D display coordinate?
  - ♦ Projections
- Conceptual viewing pipeline:



### Planar Geometric Projections

- A projection is formed by the intersection of certain lines (*projectors*) with a plane (*the projection plane*)
- Projectors are lines from the *center of projection* through each point on object
- Center of projection at infinity results in a parallel projection
- A finite center of projection results in a perspective projection





# Parallel Projection



# Orthographic Projection

 Projectors are orthogonal to projection surface, which is typically parallel to one of the coordinate planes:



### Axonometric Projections

- Allow projection plane to move relative to object.
- How many angles of a cube's corner are equal?
  - ♦ none: trimetric
  - ♦ two: dimetric
  - $\blacklozenge$  three: isometric



# Axonometric Projections



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# **Oblique Projections**

 Arbitrary relationship between projectors and projection plane.



# Perspective Projection



# Vanishing Points

 Parallel lines (not parallel to the projection plane) on the object converge at a single point on the projection plane (the *vanishing point*):



## N-point Perspective



# Orthographic Projections

- Direction of projection is normal to the projection plane.
- Typically, project onto one of the coordinate planes. For example:
  - $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x \\ y \\ 0 \\ 1 \end{bmatrix}$
- Typically, several of these projections (e.g., front, right, and top/plan views) are shown together

### **Observations**

- The rank of the matrix is 3 (= projection)
- Points on the projection plane are not changed by the perspective projection
- Let's see what happens to a point at infinity along the Z axis:

1	0	0	0	$\begin{bmatrix} 0 \end{bmatrix}$		0		$\begin{bmatrix} 0 \end{bmatrix}$	
0	1	0	0	0	0	0	⇒	0	
0	0	1	0	$  1 ^{-}$	=	1		d	
0	0	1/d	0	0		1/d		1	

• This is a vanishing point

# Perspective Projection



## Taking a Photograph

- Arrange objects
- Position and point the camera
- ◆ Choose a lens, set the zoom
- ♦ Take a picture
- Enlarge and crop to get a print

# Taking a Virtual Photograph

- ♦ Arrange objects
  - Apply modeling transformations to objects: change from object coordinates to world coordinates
- Position and point the camera
  - Position, point, and orient the virtual camera: define a transformation from world to eye coordinates
- ◆ Choose a lens, set the zoom
  - Specify a view volume: define a perspective transformation that transforms eye coordinates to canonical normalized viewing space (clip coordinates)

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# Taking a Virtual Photograph

#### ♦ Take a picture

- Project objects by applying the perspective transformation followed by a perspective divide. The result is normalized device coordinates.
- Enlarge and crop to get a print
  - Apply viewport transformation to obtain actual window coordinates.

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### The OpenGL Viewing Pipeline



### Modelview Matrix

- The initial OpenGL camera is at the origin, pointing down the negative z-axis.
- The modelview matrix is composited from simple 3D transformations:
  - ◆ glLoadIdentity
  - ◆ glTranslate, glRotate, glScale
  - ♦ glLoadMatrix, glMultMatrix
- Camera can also be positioned by the gluLookAt routine:

gluLookAt(eye<sub>x</sub>,eye<sub>y</sub>,eye<sub>z</sub>,ctr<sub>x</sub>,ctr<sub>y</sub>,ctr<sub>z</sub>,up<sub>x</sub>,up<sub>y</sub>,up<sub>z</sub>)

### Projection Matrix

Specified by defining a view volume (view frustum):

glFrustum(left, right, bottom, top, near, far)



### Projection Matrix

- Also can be specified by gluPerspective(fov, aspect, near, far)
  - ♦ aspect = w/h
  - fov = vertical field of view angle (degrees)



### Projection Matrix

 glFrustum defines the following perspective transformation matrix:

$$\begin{bmatrix} \frac{2n}{r-l} & 0 & \frac{r+l}{r-l} & 0\\ 0 & \frac{2n}{t-b} & \frac{t+b}{t-b} & 0\\ 0 & 0 & -\frac{f+n}{f-n} & \frac{-2fn}{f-n}\\ 0 & 0 & -1 & 0 \end{bmatrix}$$

### Derivation, part I

 glFrustum defines a general (possibly skewed) viewing pyramid. We first make this pyramid into a canonical one:

 $\Rightarrow$ 

 We first shear the skewed pyramid, then scale.

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### Shearing Matrix

 Transforms the center of the viewing window (on the near plane) to (0,0,-n), making the view pyramid symmetric about the Z-axis:

$$\begin{bmatrix} 1 & 0 & \frac{r+l}{2n} & 0 \\ 0 & 1 & \frac{t+b}{2n} & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

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### Scaling Matrix

 Scale the symmetric pyramid to create a 45 degree angle between each plane and the Z-axis:



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### Derivation, part II

 The canonical pyramid is then transformed into a cube, using a perspective transformation:



Finally...

 Multiplying the transformations gives us the desired matrix:

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -\frac{f+n}{f-n} & \frac{-2fn}{f-n} \\ 0 & 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} \frac{2n}{r-l} & 0 & 0 & 0 \\ 0 & \frac{2n}{t-b} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & \frac{r+l}{2n} & 0 \\ 0 & 1 & \frac{t+b}{2n} & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} \frac{2n}{r-l} & 0 & \frac{r+l}{r-l} & 0 \\ 0 & \frac{2n}{t-b} & \frac{t+b}{t-b} & 0 \\ 0 & 0 & -\frac{f+n}{f-n} & \frac{-2fn}{f-n} \\ 0 & 0 & -1 & 0 \end{bmatrix}$$

## The effect on Z



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# View Frustum Clipping

• In homogeneous coordinates all points inside the view frustum satisfy all of the following inequalities: x < w x > -ww > 0 and y < w y > -wz < w z > -w

• Lines must be clipped against the planes:

x = w x = -w y = w y = -w z = w z = -w

### Viewport Transformation

 Defines a pixel rectangle in the window into which the final image is mapped:

glViewport(x, y, width, height)

(x, y) specify the lower left corner of the viewport:



### Viewport Transformation

- Transfroms normalized device (nd) coordinates to window (w) coordinates.
- nd coordinates range in [-1,1]
- w coordinates range in [x, x+width], [y,y+height]
- The resulting transformation is:

$$x_{w} = (x_{nd} + 1) \left(\frac{width}{2}\right) + x$$
$$y_{w} = (y_{nd} + 1) \left(\frac{height}{2}\right) + y$$

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