Basic Geometry Review

Basic Geometric Entities

- Scalars real numbers
 sizes/lengths, angles
- Vectors typically 2D, 3D, 4D
 directions
- Points typically 2D, 3D, 4D
 locations

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Spaces

- Scalar field: formed by scalars and the operations between them (+,*).
- Vector space: formed by vectors, scalars, and the operations between them.
- Note: a purely abstract vector space has no notion of: distance, size, angle, or point!

Affine spaces

- An affine space adds the notion of point to the vector space: A = (P,V), where V is a vector space and P is a set of points:
 - \blacklozenge for every point p and vector v, p+v \in P
 - for every two points $p,q: p-q \in V$.
- By choosing a basis and designating an origin point, we define an affine frame:

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\mathbf{p} = \mathbf{a} + \alpha_1 \mathbf{v}_1 + \dots + \alpha_n \mathbf{v}_n
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Euclidean / Cartesian spaces **Operations on Vectors** A Euclidean space is an affine space with a Addition distance metric based on inner product: $\mathbf{u} + \mathbf{v} = [u_1 + v_1, \dots, u_n + v_n]^{\mathrm{T}}$ $|\mathbf{a}-\mathbf{b}| = \sqrt{\langle \mathbf{a}-\mathbf{b},\mathbf{a}-\mathbf{b}\rangle} = \sqrt{(\mathbf{a}_1-\mathbf{b}_1)^2 + \dots + (\mathbf{a}_n-\mathbf{b}_n)^2}$ Multiplication by a scalar Cartesian space: Euclidean space with a $s\mathbf{u} = [su_1, \ldots, su_n]^T$ standard orthonormal frame: Basis vectors have length 1 • Basis vectors are pairwise perpendicular Dot product (scalar product) (orthogonal) $\mathbf{u} \cdot \mathbf{v} = \mathbf{u}^{\mathrm{T}} \mathbf{v} = u_1 v_1 + \dots + u_n v_n$ 5 6 11/2/2005 Dani Lischinski 11/2/2005 Dani Lischinski

Operations on Vectors

Cross product (vector product)

$$\mathbf{u} \times \mathbf{v} = \begin{bmatrix} u_2 v_3 - u_3 v_2 \\ u_3 v_1 - u_1 v_3 \\ u_1 v_2 - u_2 v_1 \end{bmatrix}$$

What is the geometric meaning of these operations?

Operations on Vectors

Vector size/length/norm:

$$\left|\mathbf{v}\right| = \sqrt{\mathbf{v}_1^2 + \dots + \mathbf{v}_n^2}$$

Unit vector = pure direction

$$|\mathbf{v}| = 1$$

- ♦ General vector = size * direction
- Vector normalization:

$$\mathbf{v} \leftarrow \frac{\mathbf{v}}{|\mathbf{v}|}$$

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Operations on Points

◆ Can't add points...

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- but can add a vector to a point $\mathbf{a} + \mathbf{v} = \mathbf{b}$
- ♦ also can subtract points

 $\mathbf{v} = \mathbf{b} - \mathbf{a}$

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- ◆ Can't multiply a point by a scalar...
 - but can take the affine combination of two points: $\mathbf{c} = s\mathbf{a} + t\mathbf{b}$ where s + t = 1
 - can also take the affine combination of n > 2 points.

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Lines and Planes

- ◆ A line in 2D can be defined by:
 - all affine combinations of two points
 - implicit equation: f(x,y) = ax+by+c = 0
 - parametric equation: L(t) = O + tD
- ◆ A plane can be defined by:
 - all affine combinations of three points
 - implicit equation: f(x,y,z) = ax+by+cz+d = 0
 - parametric equation: $P(s,t) = O + sD_1 + tD_2$

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